Technology Overview

NVIDIA GeForce GTX 680

The fastest, most efficient GPU ever built.
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Introduction

Since our inception, NVIDIA has strived to bring the highest quality 3D graphics to gamers, with each new generation pushing the performance envelope, and delivering the latest graphics effects and stunning visuals for the PC platform. Enthusiast-class PC games that took full advantage of our most recent Fermi GPU generation were able to incorporate highly detailed, geometrically complex 3D graphics scenes, and convincing character renderings, animations, and physical simulations.

With the introduction of NVIDIA’s latest GPU architecture, codenamed “Kepler,” our goal was to continue to push the limits in graphics processing capabilities, and also create an extremely power-efficient GPU.

NVIDIA’s Kepler architecture builds on the foundation first established in 2010 with NVIDIA’s Fermi GPU architecture. Fermi introduced an entirely new parallel geometry pipeline optimized for tessellation and displacement mapping. This made it possible for games such as Battlefield 3, Batman: Arkham City, and Crysis 2 to use richly detailed characters and environments while retaining high performance. Kepler continues to provide the best tessellation performance and combines this with new features specifically designed to deliver a faster, smoother, richer gaming experience.

The first GPU based on our new Kepler architecture, codenamed “GK104,” is not only our highest performing GPU to date, it is also the most efficient in terms of power consumption. GK104 is fabricated on an optimized 28nm process, and every internal unit was designed for the best perf/watt possible. The first product being introduced based on GK104 is the GeForce GTX 680.

The introduction of NVIDIA’s Kepler GPU architecture will allow game developers to incorporate even greater levels of geometric complexity, physical simulations, stereoscopic 3D processing, and advanced antialiasing effects into their next generation of DX11 titles.

But the next generation of PC gaming isn’t just about clock speeds, raw performance, perf/watt, and new graphics effects. It’s also about providing consistent frame rates and a smoother gaming experience. In this whitepaper you will learn about the new smooth gaming technologies implemented in Kepler to enable this.

Performance Per Watt

When designing our prior generation Fermi GPU architecture, NVIDIA engineers focused on dramatically improving performance over the Tesla (GT200) GPU generation, with special emphasis on geometry, tessellation, and compute performance for DirectX 11. Though managing power consumption was an important consideration during Fermi’s development, achieving breakthrough levels of DX11 performance was the primary objective.

For Kepler we took a different approach. While maintaining our graphics performance leadership was still the most important goal, the overarching theme driving Kepler’s design was dramatically improving
performance per watt. NVIDIA engineers applied everything learned from Fermi to better optimize the Kepler architecture for highly efficient operation, in addition to significantly enhanced performance.

TSMC’s 28nm manufacturing process plays an important role in lowering power consumption, but many GPU architecture modifications were required to further reduce power consumption while maintaining high performance.

Every hardware unit in Kepler was designed and scrubbed to provide outstanding performance per watt.

The most notable example of great perf/watt can be found in the design of Kepler’s new Streaming Multiprocessor, called “SMX.” In SMX we saw a large opportunity to reduce GPU power consumption through a new architectural approach. For improved power efficiency, the SMX now runs at graphics clock rather than 2x graphics clock; but with 1536 CUDA cores in GK104, the GeForce GTX 680 SMX provides 2x the performance per watt of Fermi’s SM (GF110). This allows the GeForce GTX 680 to deliver revolutionary performance/watt when compared to GeForce GTX 580:

SMX’s design for power efficiency is discussed in more depth in the “Next Generation SM” section below.
Kepler Architecture In-Depth (GeForce GTX 680)

Like Fermi, Kepler GPUs are composed of different configurations of Graphics Processing Clusters (GPCs), Streaming Multiprocessors (SMs), and memory controllers. The GeForce GTX 680 GPU consists of four GPCs, eight next-generation Streaming Multiprocessors (SMX), and four memory controllers.

Figure 1: GeForce GTX 680 Block Diagram
In GeForce GTX 680, each GPC has a dedicated raster engine and two SMX units. With a total of eight SMX units, the GeForce GTX 680 implementation has 1536 CUDA Cores.

GeForce GTX 680’s memory subsystem was also completely revamped, resulting in dramatically higher memory clock speeds. Operating at 6008MHz data rate, GeForce GTX 680 offers the highest memory clock speeds of any GPU in the industry.

Tied to each memory controller are 128KB L2 cache and eight ROP units (each of the eight ROP units processes a single color sample). With four memory controllers, a full GeForce GTX 680 GPU has 512KB L2 cache and 32 ROPs (i.e., 32 color samples).

We’ll be discussing the SMXs, ROPs and other units in greater detail in the following pages. We assume you already have a basic understanding of the pipeline changes introduced with NVIDIA’s GPC architecture first implemented in Fermi. If you are not well versed in NVIDIA’s GPC architecture, we suggest you first read the GF100 whitepaper.

The following table provides a high-level comparison of Kepler vs. previous generation NVIDIA GPUs:

<table>
<thead>
<tr>
<th>GPU</th>
<th>GT200 (Tesla)</th>
<th>GF110 (Fermi)</th>
<th>GK104 (Kepler)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Transistors</td>
<td>1.4 billion</td>
<td>3.0 billion</td>
<td>3.54 billion</td>
</tr>
<tr>
<td>CUDA Cores</td>
<td>240</td>
<td>512</td>
<td>1536</td>
</tr>
<tr>
<td>Graphics Core Clock</td>
<td>648MHz</td>
<td>772MHz</td>
<td>1006MHz</td>
</tr>
<tr>
<td>Shader Core Clock</td>
<td>1476MHz</td>
<td>1544MHz</td>
<td>n/a</td>
</tr>
<tr>
<td>GFLOPs</td>
<td>1063</td>
<td>1581</td>
<td>3090</td>
</tr>
<tr>
<td>Texture Units</td>
<td>80</td>
<td>64</td>
<td>128</td>
</tr>
<tr>
<td>Texel fill-rate</td>
<td>51.8 Gigatexels/sec</td>
<td>49.4 Gigatexels/sec</td>
<td>128.8 Gigatexels/sec</td>
</tr>
<tr>
<td>Memory Clock</td>
<td>2484 MHz</td>
<td>4008 MHz</td>
<td>6008MHz</td>
</tr>
<tr>
<td>Memory Bandwidth</td>
<td>159 GB/sec</td>
<td>192.4 GB/sec</td>
<td>192.26 GB/sec</td>
</tr>
<tr>
<td>Max # of Active Displays</td>
<td>2</td>
<td>2</td>
<td>4</td>
</tr>
<tr>
<td>TDP</td>
<td>183W</td>
<td>244W</td>
<td>195W</td>
</tr>
</tbody>
</table>

The overall configuration of GTX 680 was chosen to provide a large increase in shader and texture horsepower vs. the GTX 580, while maintaining per clock operand throughputs for most other metrics (which also benefit from the increased core clock frequency).

**GPC**

The GPC continues to be the dominant high-level hardware block in Kepler. With its own dedicated resources for rasterization, shading, texturing, and compute, most of the GPU’s core graphics functions are performed inside the GPC. GeForce GTX 680 contains four GPCs, delivering 32 pixels per clock.
Next Generation SM (SMX) Overview

The SM is the heart of NVIDIA’s unified GPU architecture. Most of the key hardware units for graphics processing reside in the SM. The SM’s CUDA cores perform pixel/vertex/geometry shading and physics/compute calculations. Texture units perform texture filtering and load/store units fetch and save data to memory. Special Function Units (SFUs) handle transcendental and graphics interpolation instructions. Finally, the PolyMorph Engine handles vertex fetch, tessellation, viewport transform, attribute setup, and stream output.

One of the keys to GeForce GTX 680’s extraordinary performance is the next generation SM design, called SMX. SMX contains several important architectural changes that combine to deliver unprecedented performance and power efficiency.

To understand SMX performance, it helps to start by comparing the chip level unit counts for GeForce GTX 580 (containing 16 SMs) to GeForce GTX 680 (containing 8 SMXs):

<table>
<thead>
<tr>
<th>GPU</th>
<th>GF110 (Fermi)</th>
<th>GK104 (Kepler)</th>
<th>Ratio</th>
<th>Ratio (w/ clk freq)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Total unit counts :</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CUDA Cores</td>
<td>512</td>
<td>1536</td>
<td>3.0x</td>
<td></td>
</tr>
<tr>
<td>SFU</td>
<td>64</td>
<td>256</td>
<td>4.0x</td>
<td></td>
</tr>
<tr>
<td>LD/ST</td>
<td>256</td>
<td>256</td>
<td>1.0x</td>
<td></td>
</tr>
<tr>
<td>Tex</td>
<td>64</td>
<td>128</td>
<td>2.0x</td>
<td></td>
</tr>
<tr>
<td>Polymorph</td>
<td>16</td>
<td>8</td>
<td>0.5x</td>
<td></td>
</tr>
<tr>
<td>Warp schedulers</td>
<td>32</td>
<td>32</td>
<td>1.0x</td>
<td></td>
</tr>
<tr>
<td>Throughput per graphics clock :</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>FMA32</td>
<td>1024</td>
<td>1536</td>
<td>1.5x</td>
<td>2.0x</td>
</tr>
<tr>
<td>SFU</td>
<td>128</td>
<td>256</td>
<td>2.0x</td>
<td>2.6x</td>
</tr>
<tr>
<td>LD/ST (64b operations)</td>
<td>256</td>
<td>256</td>
<td>1.0x</td>
<td>1.3x</td>
</tr>
<tr>
<td>Tex</td>
<td>64</td>
<td>128</td>
<td>2.0x</td>
<td>2.6x</td>
</tr>
<tr>
<td>Polygon/clk</td>
<td>4</td>
<td>4</td>
<td>1.0x</td>
<td>1.3x</td>
</tr>
<tr>
<td>Inst/clk</td>
<td>32*32</td>
<td>64*32</td>
<td>2.0x</td>
<td>2.6x</td>
</tr>
</tbody>
</table>

At the chip level, the per-clock throughput for key graphics operations (FMA32, SFU operations, and texture operations) have all been increased substantially, while other operations retain per-clock throughput equal to GeForce GTX 580. GeForce GTX 680’s substantially higher clock frequency provides a further throughput boost for all operations.

For GeForce GTX 680, we chose—for area efficiency reasons—to divide the aggregate horsepower into 8 total SMX units (rather than dividing the aggregate horsepower into 16 SM units as we did in GeForce GTX 580). Considering this and the other factors above, the per-SMX unit count and throughput can be compared as follows:

<table>
<thead>
<tr>
<th>GPU</th>
<th>GF110 (Fermi)</th>
<th>GK104 (Kepler)</th>
<th>Ratio</th>
<th>Ratio (w/ clk freq)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Per SM unit counts :</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CUDA Cores</td>
<td>32</td>
<td>192</td>
<td>6.0x</td>
<td></td>
</tr>
<tr>
<td>Functional Unit</td>
<td>Count</td>
<td>Throughput</td>
<td>Throughput</td>
<td></td>
</tr>
<tr>
<td>--------------------------</td>
<td>-------</td>
<td>------------</td>
<td>------------</td>
<td></td>
</tr>
<tr>
<td>SFU</td>
<td>4</td>
<td>32</td>
<td>8.0x</td>
<td></td>
</tr>
<tr>
<td>LD/ST</td>
<td>16</td>
<td>32</td>
<td>2.0x</td>
<td></td>
</tr>
<tr>
<td>Tex</td>
<td>4</td>
<td>16</td>
<td>4.0x</td>
<td></td>
</tr>
<tr>
<td>Polymorph</td>
<td>1</td>
<td>1</td>
<td>1.0x</td>
<td></td>
</tr>
<tr>
<td>Warp schedulers</td>
<td>2</td>
<td>4</td>
<td>2.0x</td>
<td></td>
</tr>
</tbody>
</table>

Throughput per graphics clock:

<table>
<thead>
<tr>
<th>Functional Unit</th>
<th>Count</th>
<th>Throughput</th>
<th>Throughput</th>
</tr>
</thead>
<tbody>
<tr>
<td>FMA32</td>
<td>64</td>
<td>192</td>
<td>3.0x</td>
</tr>
<tr>
<td>SFU</td>
<td>8</td>
<td>32</td>
<td>4.0x</td>
</tr>
<tr>
<td>LD/ST (64b operations)</td>
<td>16</td>
<td>32</td>
<td>2.0x</td>
</tr>
<tr>
<td>Tex</td>
<td>4</td>
<td>16</td>
<td>4.0x</td>
</tr>
<tr>
<td>Polygon/clk</td>
<td>0.25</td>
<td>0.5</td>
<td>2.0x</td>
</tr>
<tr>
<td>Inst/clk</td>
<td>32*2</td>
<td>32*8</td>
<td>4.0x</td>
</tr>
</tbody>
</table>

See below for the block diagram illustration of the functional units in SMX.
Figure 2: GeForce GTX 680 SMX
To feed the execution resources of SMX, each unit contains four warp schedulers, and each warp scheduler is capable of dispatching two instructions per warp every clock.

More importantly, the scheduling functions have been redesigned with a focus on power efficiency. For example: Both Kepler and Fermi schedulers contain similar hardware units to handle scheduling functions, including, (a) register scoreboarding for long latency operations (texture and load), (b) inter-warp scheduling decisions (e.g., pick the best warp to go next among eligible candidates), and (c) thread block level scheduling (e.g., the GigaThread engine); however, Fermi’s scheduler also contains a complex hardware stage to prevent data hazards in the math datapath itself. A multi-port register scoreboard keeps track of any registers that are not yet ready with valid data, and a dependency checker block analyzes register usage across a multitude of fully decoded warp instructions against the scoreboard, to determine which are eligible to issue.

For Kepler, we realized that since this information is deterministic (the math pipeline latencies are not variable), it is possible for the compiler to determine up front when instructions will be ready to issue, and provide this information in the instruction itself. This allowed us to replace several complex and power-expensive blocks with a simple hardware block that extracts the pre-determined latency information and uses it to mask out warps from eligibility at the inter-warp scheduler stage.

We also developed a new design for the processor execution core, again with a focus on best performance per watt. Each processing unit was scrubbed to maximize clock gating efficiency and minimize wiring and retiming overheads.
The biggest visible change for the processor core is the elimination of shader clock. Shader clock was introduced in the Tesla architecture as an area optimization. Running execution units at a higher clock rate allows a chip to achieve a given target throughput with fewer copies of the execution unit.

However, the higher clock rate also implies more power, especially clock power. Doubling the clock frequency implies twice as many pipeline stages, each running at twice the clock rate—so 4x power per unit. Even with half as many units required for a given throughput target, a 2x power penalty for the retiming stage units remains.

For Kepler, our priority was perf/W. While we made many optimizations that benefitted both area and power, this was an example of a case where we chose to optimize for power even at the expense of added area.

### PolyMorph Engine 2.0

The final SMX unit to receive significant modifications in Kepler is the PolyMorph Engine. The PolyMorph Engine is the key unit responsible for Fermi’s extraordinary performance on DX11 tessellation workloads. It is designed to ensure that even as tessellation is increased to very high expansion factors (i.e., ratio of output polygons emitted per input patch), the impact on rendering performance is minimized.

GeForce GTX 680 contains 8 PolyMorph Engines, compared to 16 for GeForce GTX 580; however, the Kepler PolyMorph engine was redesigned to deliver roughly double the per-clock performance of the Fermi version. GeForce GTX 680’s 30% higher shipping clock speed ensures a significant overall improvement in tessellation workloads.
Overall, GeForce GTX 680 provides a significant tessellation performance boost vs. GeForce GTX 580. Compared to the competition, GeForce GTX 680 also maintains a large performance lead at high expansion factors, which we expect will become increasingly important as developers increase their usage of tessellation and begin authoring content natively, assuming a tessellation-capable API.

![Microsoft SubD11 SDK Test](image)

**L2 Cache**

In addition to offering dedicated L1, texture, uniform, and instruction caches, Kepler also features a unified 512KB L2 cache that provides an additional storage buffer for the above-listed units and is shared across the GPU.

To support the increased processing horsepower of the SMX cores, GeForce GTX 680’s L2 cache hit bandwidth has increased by 73%. Atomic operation throughput has also been significantly increased—particularly for atomic operations to a single common address. The following table summarizes GeForce GTX 580 vs. GeForce GTX 680 throughput for L2 operations:

<table>
<thead>
<tr>
<th></th>
<th>GF110 (Fermi)</th>
<th>GK104 (Kepler)</th>
<th>Ratio (w/ clk freq)</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>L2 Bandwidth</strong></td>
<td>384B/clk</td>
<td>512B/clk</td>
<td>1.3x</td>
</tr>
<tr>
<td><strong>Atomic op (shared address)</strong></td>
<td>1/9th per clock</td>
<td>1 per clock</td>
<td>9.0x</td>
</tr>
<tr>
<td><strong>Atomic op (independent address)</strong></td>
<td>24 per clock</td>
<td>64 per clock</td>
<td>2.7x</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>1.7x</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>11.7x</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>3.5x</td>
</tr>
</tbody>
</table>
**Bindless Textures**

Prior to Kepler, for the GPU to reference a texture, it had to be assigned a “slot” in a fixed-size binding table. The number of slots in that table ultimately limits how many unique textures a shader can read from at run time. Ultimately, a shader was limited to access of just 128 simultaneous textures in Fermi (which aligned with the API limits of DX11).

With bindless textures in Kepler, this additional step isn’t necessary: the shader can reference textures directly in memory, making binding tables obsolete. This effectively eliminates any limits on the number of unique textures that can be used to render a scene: over 1 million unique textures are possible.

Besides dramatically increasing the number of available textures, another added benefit of bindless textures is reduced CPU utilization:
At this time, bindless textures is only exposed in OpenGL. But in the future it’s possible this could be exposed in DirectX via NVAPI, or future versions of DirectX.

**World’s Fastest GDDR5**

For Kepler, the memory team developed a completely new IO design built to push to the theoretical limits of GDDR5 signaling speed. In order to meet this ambitious goal, extensive improvements in circuit and physical design, link training, and signal integrity were made based on in-depth study of our existing silicon. The significant improvement in speed was only made possible by a highly integrated cross-functional effort that enables the co-optimization of these three major areas of improvements. The result was the industry’s first 6Gbps GDDR5 product.
GPU Boost

When determining the thermal design power (TDP) limit of our GPUs, NVIDIA engineers monitor the GPU’s power consumption while running a wide range of real-world 3D applications in a worst-case thermal environment. We then set the GPU’s clock speeds based on these results.

Under real world conditions running today’s latest games, however, most GPUs will never approach their TDP; power consumption varies from one application to another, and most users don’t run their GPUs under worst-case environmental conditions.

In cases where the GPU isn’t fully taxed, it would be beneficial if the GPU could increase its clock frequency to deliver improved 3D performance and/or higher image quality with richer graphics effects enabled. This is where NVIDIA’s GPU Boost technology comes in.

A combination of hardware and software technology that works with the GeForce GTX 680, GPU Boost works in the background, dynamically adjusting the GPU’s graphics clock speed automatically, based on GPU operating conditions. Dedicated hardware circuitry continually monitors GPU power consumption. GPU Boost automatically adjusts clocks to achieve the maximum possible clock speed while remaining within a predefined power target.

![NVIDIA GPU Boost Uses Available Power](image)

170W is the typical board power NVIDIA has defined for the GeForce GTX 680 and GPU Boost. Under load, most cards will typically operate at this power level. After careful consideration, we ultimately determined this power level delivers the optimal combination of GPU power, temps, and acoustics, providing an exquisite experience for GeForce GTX 680 users.
GPU Boost operates completely autonomously with no game profiles and no intervention required by the end user, providing an instant performance boost to gamers.

GeForce GTX 680’s base 3D frequency is 1006MHz, which is called the “Base Clock.” This is the minimum 3D frequency the GPU is guaranteed to achieve running under load in TDP apps (strenuous real-world applications that push power utilization to the Thermal Design Power limits of a GPU).

The “Boost Clock” is the average clock frequency the GPU will run under load in many typical non-TDP apps that require less GPU power consumption. On average, the typical Boost Clock provided by GPU Boost in GeForce GTX 680 is 1058MHz, an improvement of just over 5%. The Boost Clock is a typical clock level achieved while running a typical game in a typical environment.

However, in many cases the GPU will have additional power headroom available and will automatically increase the Boost Clock even higher than 1058MHz. As long as the GPU remains under its power target, GPU Boost will seamlessly increase the GPU Clock: clock speeds of 1.1GHz or higher have been observed internally in testing various non-TDP apps.

GPU Boost is fully compatible with GPU overclocking. Using third-party overclocking utilities provided by NVIDIA board partners, GeForce GTX 680 users can adjust the GPU’s power target to enable higher clock speeds. Once the power target has been increased, the GPU can be overclocked by raising the GPU clock offset. As you can see in the screenshot below, some GeForce GTX 680 cards are able to scale to much higher clock speeds:

![Figure 3: GeForce GTX 680 runs Heaven at over 1.2GHz with complete stability!](image-url)
Adaptive VSync

Long ago, game content was rendered by presenting new frames synchronously with display refresh intervals (aka Vertical sync.). However, this approach leads to a noticeable stuttering or hitching effects whenever the rendering rate drops below the refresh rate (typically 60Hz)—if the rendering rate is only a little slower, the synchronization step will drop from 60Hz to 30Hz (and other multiples of 60, such as 20 or 15Hz), leading to stuttering.

![VSync Stutters When Frame Rates Droop](image)

To avoid this undesirable effect, one approach has been to run with VSync disabled. Instead, new frames are presented immediately, with a “tear line” visible on the screen at the switch point between old and new frames. This is a better approach at low frame rates, but when rendering is fast, the tearing introduces an unnecessary and very noticeable visual artifact. Tearing can be visually distracting to the end user, leading to a less enjoyable gaming experience. (Tearing can also occur when frame rates are less than the refresh rate, but it’s more noticeable at higher fps.)
To tackle this challenge, NVIDIA software engineers have developed Adaptive VSync. NVIDIA’s Adaptive VSync technology, introduced with our Release 300 drivers, dynamically varies VSync on and off to display frames at a more regular cadence, minimizing stuttering in games.

When frame rates drop below 60 frames per second, NVIDIA Adaptive VSync technology automatically disables VSync, allowing frame rates to run at their natural rate, effectively reducing stutter. Once frame rates return to 60 fps, Adaptive VSync turns VSync back on to reduce tearing.

The end result is a smoother, more enjoyable gaming experience.
Adaptive VSync is a new feature shipping with our R300 drivers and is compatible with GeForce GTX 680 as well as prior generation GeForce GPUs. Adaptive VSync can be found within the Vertical sync setting in the NVIDIA control panel:

Two Adaptive VSync options are available within the control panel: Adaptive and Adaptive (half refresh rate).

The half refresh rate option is useful in situations where your performance is generally between 25 – 50 frames per second. In these cases, the half refresh rate setting will lock VSync at 30 when frame rates are 30 fps or more, and dynamically turn VSync off as the frame rate goes below 30 fps for a smoother experience with reduced stuttering.
FXAA

NVIDIA FXAA technology harnesses the power of the GPU’s CUDA Cores to reduce visible aliasing. FXAA is a pixel shader-based image filter that is applied along with other post processing steps like motion blur and bloom. For game engines making use of deferred shading, FXAA provides a performance and memory advantage over deferred shading with multi-sample anti-aliasing (MSAA).

FXAA targets edge aliasing and also aliasing on single-pixel and sub-pixel sized features, which tend to flicker as they move from frame to frame. FXAA reduces the visual contrast of these features so that they are less jarring to the eye. Note that FXAA cannot completely solve the sub-pixel aliasing problem, but it does substantially reduce it. The overall effect is smoother visual quality.

FXAA reduces but does not completely eliminate shader aliasing. FXAA’s chief advantage over traditional MSAA is higher performance. In many cases, FXAA can be applied at a cost of 1ms per frame or less, resulting in frame rates that are often 2x higher than 4xMSAA with comparable image quality.

NVIDIA FXAA was first implemented in games last year beginning with *Age of Conan*. Since then, FXAA has shipped in 15 additional titles.

FXAA has been added to the driver control panel beginning with the release of our R300 drivers. With FXAA support now built in to the graphics driver, FXAA can be enabled in hundreds of games.
Please note that there are multiple versions of FXAA:

- **Developer-integrated FXAA**: Initial versions of FXAA (FXAA 1) shipped with games like Age of Conan, F.E.A.R.3, and Duke Nukem Forever. It was designed to provide high visual quality, at the cost of slower performance. The most current version of FXAA (FXAA 3) is available for game developers to integrate into their game engines as a drop-in AA solution. It provides a more optimal combination of performance and image quality than the original version of FXAA and it works across DX9 through DX11 and OpenGL. It has a configurable performance, quality, and sharpness tradeoff that will vary from title to title depending on what choices the developer makes during integration. FXAA 3 is used in Battlefield 3.

- **Control-panel FXAA**: This is the version used in the R300 driver control panel. It is a mixture of FXAA 1 and FXAA 3 with some modifications to look better than FXAA 1 on text. In comparison to FXAA 3 integrated into games, control-panel FXAA will provide better image quality except for the HUD and text, since it is applied after they are rendered in the graphics pipeline. This version of FXAA also performs slower than FXAA 3.

As you can see, over the last year FXAA has evolved to become a popular AA option for game developers who need a high performance AA solution that can be tweaked to their specific game engine needs. Gamers benefit because they can play their favorite games with high image quality without paying the performance tax of MSAA; and now that we’re providing a driver-based FXAA option that’s built-in to the control panel, gamers can experience the benefits of FXAA firsthand in most of their games.

**NOTE:** If you would like to take screenshots of our control panel-based FXAA while in-game, you will need to press the Print Screen button. FRAPS isn’t able to capture screenshots that accurately reflect our driver-based control panel FXAA.
At the Game Developers Conference in San Francisco last year, Epic demonstrated their Samaritan demo, providing a sneak peak at what next-generation DX11 games may look like. Running on three GeForce GTX 580 GPUs in 3-Way SLI configuration, the Samaritan demo stunned the crowd with its DX11 tessellation and displacement mapping, subsurface scattering, depth of field, reflections, dynamic shadows, and more.

Utilizing the power of the Kepler architecture and NVIDIA FXAA technology, one year later that same demo can now be run on one GeForce GTX 680 GPU!
TXAA

TXAA is a new film-style AA technique that is designed to exploit GeForce GTX 680’s high FP16 texture performance. TXAA is a mix of hardware anti-aliasing, custom CG film style AA resolve, and in the case of 2xTXAA, an optional temporal component for better image quality. The bulk of TXAA is a high-quality resolve filter, which is carefully designed to work with the HDR-correct post processing pipeline.
TXAA is available with two modes: TXAA 1, and TXAA 2. TXAA 1 offers visual quality on par with 8xMSAA with the performance hit of 2xMSAA, while TXAA 2 offers image quality that is superior to 8xMSAA, but with performance comparable to 4xMSAA.
Like our FXAA technology, TXAA will first be implemented in upcoming game titles shipping later this year.

The following games and game engines/developers have committed to offering TXAA support so far: *MechWarrior Online, Secret World, Eve Online, Borderlands 2*, Unreal 4 Engine, BitSquid, Slant Six Games, and Crytek.
New Display/Video Engine

All Kepler GPUs feature an all-new display engine that has been tailored for next-generation 4k and 3GHz HDMI displays, multi-display gaming with NVIDIA Surround, multi-stream audio, and enhanced video transcoding.

GeForce GTX 680’s display engine is capable of driving up to four displays simultaneously, and provides native Surround support from one GeForce GTX 680 card.

![Image: Up to 4 Displays on a Single Card]

*Figure 4: GeForce GTX 680 natively supports up to 4 display gaming*

The GeForce GTX 680 reference board design ships with two dual-link DVI connectors, as well as HDMI and DisplayPort outputs. Based on NVIDIA research, DVI is still the most common display output. And with full-size HDMI and DisplayPort connections, no adapters are needed to support most displays on the market.

**NVENC**

All Kepler GPUs also incorporate a new hardware-based H.264 video encoder, NVENC.

Prior to the introduction of Kepler, video encoding on previous GeForce products was handled by encode software running on the GPU’s array of CUDA Cores. While the CUDA Cores were able to deliver tremendous performance speedups compared to CPU-based encoding, one downside of using these high-speed processor cores to process video encoding was increased power consumption.

By using specialized circuitry for H.264 encoding, the NVENC hardware encoder in Kepler is almost four times faster than our previous CUDA-based encoder while consuming much less power.
It is important to note that an application can choose to encode using both NVENC hardware and NVIDIA’s legacy CUDA encoder in parallel, without negatively affecting each other. However, some video pre-processing algorithms may require CUDA, and this will result in reduced performance from the CUDA encoder since the available CUDA Cores will be shared by the encoder and pre-processor.

NVENC provides the following:

- Can encode full HD resolution (1080p) videos up to 8x faster than real-time. For example, in high performance mode, encoding of a 16 minute long 1080p, 30 fps video will take approximately 2 minutes.
- Support for H.264 Base, Main, and High Profile Level 4.1 (same as Blu-ray standard)
- Supports MVC (Multiview Video Coding) for stereoscopic video—an extension of H.264 which is used for Blu-ray 3D.
- Up to 4096x4096 encode

We currently expose NVENC through proprietary APIs, and provide an SDK for development using NVENC. Later this year, CUDA developers will also be able to use the high performance NVENC video encoder. For example, you could use the compute engines for video pre-processing and then do the actual H.264 encoding in NVENC. Alternatively, you can choose to improve overall video encoding performance by running simultaneous parallel encoders in CUDA and NVENC, without affecting each other’s performance.

NVENC enables a wide range of new use cases for consumers:

- HD videoconferencing on mainstream notebooks
- Sending the contents of the desktop to the big screen TV (gaming, video) through a wireless connection
- Authoring high quality Blu-ray discs from your HD camcorder

A beta version of Cyberlink MediaEspresso with NVENC support is now available on the GeForce GTX 680 press FTP. Support will be coming soon for Cyberlink PowerDirector and Arcsoft MediaConverter.
Conclusion

Through a combination of hardware and software advancements, GeForce GTX 680 has been crafted to provide PC gamers with a delightful gaming experience.

GeForce GTX 680’s new SMX unit features a number of architecture changes that allow it to deliver unparalleled levels of performance and power efficiency. In order to reduce power consumption while still improving GPU performance, we have eliminated the shader clock and significantly increased the number of CUDA Cores, Special Function Units, and texture units. In addition, the SMX PolyMorph Engine has been redesigned to deliver roughly double the performance of the unit used in Fermi. To improve performance even further, GeForce GTX 680 also features new GPU Boost technology that automatically increases the graphics clock speed to maximize frame rate in games.

GeForce GTX 680 supports a number of new features that have been designed to deliver a smoother experience for gamers. NVIDIA Adaptive VSync technology dynamically turns VSync on and off as needed for reduced tearing and stutter. NVIDIA FXAA technology—already a hit with gamers—is now coming to the GeForce GTX 680’s driver control panel. Lastly, TXAA, an upcoming AA technique developed by NVIDIA, brings greater than 8xMSAA image quality at the performance cost of 4xMSAA.

Offering built-in support for up to four displays, one GeForce GTX 680 card natively supports 3D Vision Surround. GeForce GTX 680 also features a new hardware-based H.264 video encoder, NVENC. NVENC is almost four times faster than our previous CUDA-based encoder while consuming much less power.

With its new SMX architecture and increased clock speeds provided by GPU Boost, the GeForce GTX 680 delivers breakthrough levels of performance and power efficiency. With advancements like Adaptive VSync, FXAA, and TXAA, games have never looked and run smoother. And the ability to run 3D Vision Surround on a single GTX 680 provides gamers with a richer experience.

The GeForce GTX 680 is the “must-have” GPU for enthusiast gamers today. It’s the fastest, most efficient GPU ever built.
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